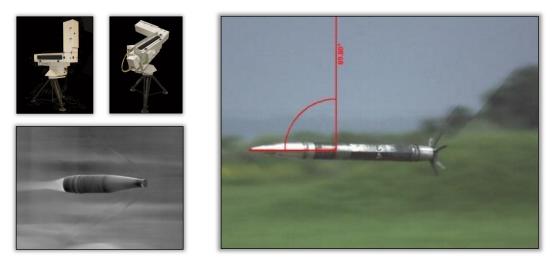
MS Instruments

AUTOMATED FLIGHT-FOLLOWER TYPE 631

Revolutionary Projectile Imaging



AUTOMATED FLIGHT-FOLLOWER TYPE 631

The Flight-Follower has been developed to meet the highspeed-imaging needs of modern ammunition designers.

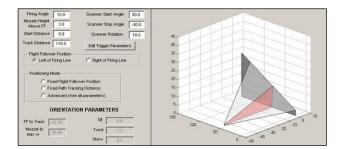
The system consists of a computer controlled triggered rotating mirror positioned in front of a High Speed Video camera. The mirror is programmed to rotate at the correct speed, such that the camera will "follow" the projectile. Typically, the system will track the trajectory for 100m or more as the mirror scans a 90° arc, providing high quality images of the projectile in flight.

This latest design offers much improved performance whilst eliminating the need for calibration. The combined functionality of the hardware and software greatly simplifies system operation without limiting flexibility.

HIGH QUALITY IMAGING

Simple and Versatile Equipment:

- Simplified range surveying
- Accommodates a variety of cameras
- High mechanical stability



Time and Effort Saving:

- Easy, quick set up
- Remote operation
- Automatic adjustment to data entries



Efficient and Optimised System:

- Software wizards
- In-built instrumentation
- Real-time mirror position control



HARDWARE

- Velocity profile modes (Fixed, Measured, Multiple Update or User-defined) with multiple trigger inputs (up to 256) and built-in trigger delay.
- Housing accommodates most High Speed Video cameras, and allows camera focusing without obscuring the flight path.
- *Mirror Halt* function stops the mirror in mid-flight for impact analysis.
- High optical throughput due to large mirror, angled optical axis, and optical components optimised for visible or infrared applications.
- High mechanical stability with benefit of remote/automated tilt, skew, and twist.
- Double axis or extended trajectory analysis using two or more synchronised units.

SOFTWARE

- Remote Operation via dedicated MS Windows software (with set-up wizards) ensures optimised set-up for all geometries including *Horizontal, Inclined,* and *Skewed*.
- Real-time (10MHz) mirror position control enables in-flight velocity and acceleration correction.
- Video analysis software supplied if required.

SPECIFICATION

| CONFIGURATIONS | | MIRROR | |
|-----------------------|---|--|------------------------------|
| Operation Modes | Measure/Fixed/Multiple Update or | Scan Ratio* (highest) | 0.1 - 100 |
| | User-defined velocity profile | Tracking Angle | 100° total, 90° tracking |
| | • 3 x TTL | Angular Tracking Accuracy | Better than 0.1° |
| | • 3 x Skyscreen | Flatness | ¼ Wave |
| | • 1 x Multi-trigger (up to 256 inputs) | *Scan Ratio = Projectile Velocity ÷ Stand-off Distance | |
| Power | 100 – 240V, 50 – 60Hz | ENVIRONMENT | |
| Trigger Output | • 1 x +5V TTL in synchronism with the | Operating Temperature | 0°C - +40°C |
| | start of the mirror scan | | [+32 F - +104 F] |
| | • 2 x TTL stand-alone (for 3-D scan etc.) | DIMENSIONS | |
| Communication | RS 232/RS485/GBit Ethernet/Fibre | L x W x H (mirror) | 3mm x 133mm x 88mm |
| | Optic/Wireless LAN | | [0.12 in x 5.24in x 3.46in] |
| HOUSING | | OPTIONS | |
| Rotation Range | • Pitch: -17 - +90° | Dual AFF System | Linked systems with 3-D view |
| (about mirror | • Roll: ±45° | | and 3-D software analysis |
| axis) | • Yaw: ±12° | - | · · · · |
| Rotation | 10.19 | | |
| Measurement | ±0.1° | | |

USED WITH







Multiple Trigger System Type 630-320

Flash Detector Type 768

Optical Detector Type 858



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The information in this document is correct at the stated time. MS Instruments Ltd has a policy of continuing development and reserves the right to make design changes/improvements to the products.